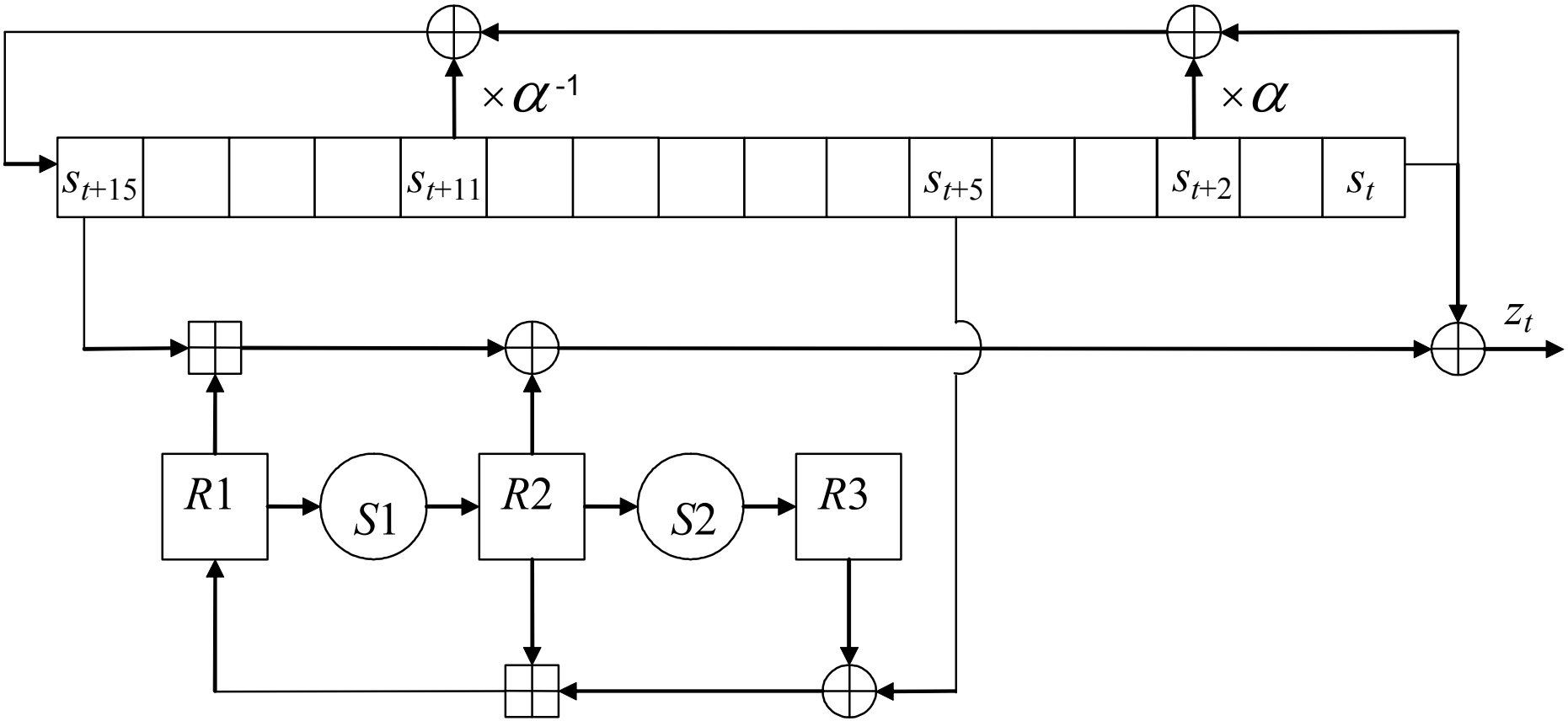
$\times\alpha^{-1}$
$\times\alpha$
s_{t+15}
s_{t+11}
s_{t+5}
s_{t+2}
s_t
z_t
R1
S1
R2
S2
R3